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EDM
11/29/10

$$\frac{dA}{dt} = \underline{K} A + Q C_p(t)$$

$$\begin{bmatrix} \dot{F} \\ \dot{B} \end{bmatrix} = \begin{bmatrix} -k_2 - k_3 & k_4 \\ k_3 & -k_4 \end{bmatrix} \begin{bmatrix} F \\ B \end{bmatrix} + \begin{bmatrix} K_1 \\ 0 \end{bmatrix} C_p$$

$$A(t) = U_n^{-1} A = [1 \ 1] \begin{bmatrix} F \\ B \end{bmatrix} = F + B$$

integrate both sides

$$A = \underline{K} \int A dt + \underline{Q} \int C_p(t) dt$$

$$\underline{K}^{-1} A = \int A dt + \underline{K}^{-1} \underline{Q} \int C_p dt$$

column vector

sum components on both sides.

$$U_n^{-1} \underline{K}^{-1} A = U_n^{-1} \int A dt + U_n^{-1} \underline{K}^{-1} \underline{Q} \int C_p dt$$

rearrange.

$$U_n^{-1} \int A dt = -U_n^{-1} \underline{K}^{-1} \underline{Q} \int C_p dt + U_n^{-1} \underline{K}^{-1} A$$

in Logan terminology $ROI(t) = U_n^{-1} A + V_p C_p$

so

$$\int ROI dt = \int U_n^{-1} A dt + V_p \int C_p dt$$

$$\int U_n^{-1} A dt = \int ROI dt - V_p \int C_p dt$$

substitute ...

Substitute for $\int U_n' A dt$ and move V_p to right (2)

$$\int ROI dt = \left(\frac{-U_n' K^{-1} Q + V_p}{U_n' A + V_p C_p} \right) \int C_p dt + \frac{U_n' K^{-1} A}{U_n' A + V_p C_p} \quad \text{EDM} \quad 11/29$$

divide by $U_n' A + V_p C_p = ROI(t)$

$$\frac{\int_0^T ROI(t) dt}{ROI(T)} = \left(\frac{-U_n' K^{-1} Q + V_p}{U_n' A + V_p C_p} \right) \frac{\int_0^T C_p(t) dt}{ROI(T)} + \frac{U_n' K^{-1} A}{U_n' A + V_p C_p}$$

for $t > t^*$

$$\frac{U_n' K^{-1} A}{U_n' A + V_p C_p} \text{ is constant.}$$

occurs when $\frac{A}{C_p} = R$ const.

show paper difference

assume $U_n' A + V_p C_p \propto C_p$ after t^*

$$= U_n' \begin{bmatrix} R_1 \\ R_2 \\ \vdots \end{bmatrix} C_p + V_p C_p$$

$$\equiv R_0 \cdot C_p$$

divide both sides by C_p instead of ROI

so . . . where $C_p =$

Then divide by $C_p(T)$

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$$\frac{\int_0^T ROI(t) dt}{C_p(T)} = \left(\underline{U_n}^{-1} \underline{K}^{-1} Q + V_p \right) \frac{\int C_p(t) dt}{C_p(T)} + \frac{\underline{U_n}^{-1} \underline{K}^{-1} A}{C_p}$$

but he assumes that $A = \begin{bmatrix} F \\ B \\ 1 \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix} C_p$

or ~~$A = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix} C_p$~~ $R = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix}$

$$\Rightarrow \frac{\int ROI(t) dt}{C_p(T)} = \left(\underline{U_n}^{-1} \underline{K}^{-1} Q + V_p \right) \frac{\int C_p(t) dt}{C_p(T)} + \underline{U_n}^{-1} \underline{K}^{-1} R$$

So where did $\begin{bmatrix} R_1 \\ R_2 \end{bmatrix}$ go in y, mx terms?

doesn't matter as long as we plot

$$\frac{\int_0^T ROI(t) dt}{C_p(T)} \quad \text{vs} \quad \frac{\int C_p(t) dt}{C_p(T)}$$

only thing that changes on plot is intercept.

Questions.

1. why less noise than logan plot. ?
2. What about 'validating approx conditions' is different from logan plot.
3. Why didn't Zhou say that logan had proposed this eqn in 2003.
(She thought it would be later and this x-out more data)